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Multiple Response Variables Regression Models in R: The mcglm Package

Wagner Hugo Bonat

Paraná Federal University University of Southern Denmark

Abstract

This article describes the R package mcglm implemented for fitting multivariate covariance generalized linear models (McGLMs). McGLMs provide a general statistical modeling framework for normal and non-normal multivariate data analysis, designed to handle multivariate response variables, along with a wide range of temporal and spatial correlation structures defined in terms of a covariance link function and a matrix linear predictor involving known symmetric matrices. The models take non-normality into account in the conventional way by means of a variance function, and the mean structure is modeled by means of a link function and a linear predictor. The models are fitted using an estimating function approach based on second-moment assumptions. This provides a unified approach to a wide variety of different types of response variables and covariance structures, including multivariate extensions of repeated measures, time series, longitudinal, genetic, spatial and spatio-temporal structures. The mcglm package allows a flexible specification of the mean and covariance structures, and explicitly deals with multivariate response variables, through a user friendly formula interface similar to the ordinary glm function. Illustrations in this article cover a wide range of applications from the traditional one response variable Gaussian mixed models to multivariate spatial models for areal data using the multivariate Tweedie distribution. Additional features, such as robust and bias-corrected standard errors for regression parameters, residual analysis, measures of goodness-of-fit and model selection using the score information criterion are discussed through six worked examples. The mcglm package is a full R implementation based on the Matrix package which provides efficient access to BLAS (basic linear algebra subroutines), Lapack (dense matrix), TAUCS (sparse matrix) and UMFPACK (sparse matrix) routines for efficient linear algebra in R.

Keywords: multivariate regression models, estimating functions, mixed outcomes, semi-parametric models, Tweedie distribution, Poisson-Tweedie distribution, R.

1. Introduction

The mcglm package (Bonat 2018) for R (R Core Team 2017) provides functions to fit and analyze multivariate covariance generalized linear models (McGLMs; Bonat and Jørgensen 2016). The package is designed to take full advantage of the modular specification of the models using a glm style interface. Additional features include robust and bias-corrected standard errors for regression parameters, measures of goodness-of-fit and residual analysis. The mcglm package is a full R implementation based on the Matrix (Bates and Maechler 2017) package which provides efficient access to C and Fortran 90 libraries such as BLAS (basic linear algebra subroutines), Lapack (dense matrix), TAUCS (sparse matrix) and UMFPACK (sparse matrix) routines for efficient linear algebra in R. Package mcglm is available from the Comprehensive R Archive Network (CRAN) at https://CRAN.R-project.org/package=mcglm.

McGLMs are fitted by means of quasi-likelihood and Pearson estimating functions, based on second-moment assumptions, and implemented in an efficient Newton scoring algorithm (Bonat and Jørgensen 2016; Jørgensen and Knudsen 2004). The mean structure for each response variable is specified in the orthodox way by means of a link function and a linear predictor. Similarly, the covariance structure for each response variable is defined in terms of a covariance link function combined with a matrix linear predictor involving known symmetric matrices. The models take non-normality into account by means of a variance function. Finally, the generalized Kronecker product (Martinez-Beneito 2013) is employed to specify the joint covariance matrix for all response variables involved in the model.

The main features of the McGLMs framework include the ability to deal with most common types of response variables, such as continuous, count, proportions and binary/binomial. Characteristics such as symmetry or asymmetry, excess zeros and overdispersion are easily handled by choosing a variance function. We can model many different types of dependence, such as those present in repeated measures, longitudinal, time series, genetic, spatial and spatio-temporal data by different specifications of the covariance link function and the matrix linear predictor. Furthermore, all these features extend to multivariate response variables using the generalized Kronecker product allowing to compute the correlation between response variables.

The analysis of non-normal multivariate data currently involves a choice between a considerable array of statistical modeling frameworks. Possible approaches include the generalized linear mixed models (GLMMs; Verbeke, Fieuws, Molenberghs, and Davidian 2014; Fieuws, Verbeke, and Molenberghs 2007), models based on copulas (Krupskii and Joe 2013) and in particular Gaussian copula marginal models (Masarotto and Varin 2012), hierarchical generalized linear models (Lee and Nelder 1996) and generalized estimating equations (Liang and Zeger 1986; Liang, Zeger, and Qaqish 1992) to cite a few.

Although all aforementioned methodologies can deal with multivariate response variables, currently software implementations have been focused on models for one dependent response variable. Furthermore, different types of dependence such as those present in repeated measures, longitudinal, genetic and spatial data may demand different software packages. It is interesting to note that well-established R packages such as **lme4** (Bates, Mächler, Bolker, and Walker 2015) and **nlme** (Pinheiro, Bates, DebRoy, Sarkar, and R Core Team 2017) do not deal with multivariate response variables. In the Bayesian context the flexible packages **INLA** (Lindgren and Rue 2015) and **MCMCpack** (Martin, Quinn, and Park 2011) do not

handle multivariate response variables, judging from the package documentation. The package gcmr (Masarotto and Varin 2017) implements Gaussian copula regression models in R. This package provides a rich set of models to model the covariance structure, but is limited to handle one response variable. Similarly, the package hglm (Rönnegård, Shen, and Alam 2010) provides functions to fit hierarchical generalized linear models along with a large set of models to describe the covariance structure, but is also limited to deal with one response variable. GEE models can be fitted in R by one of the following packages: geeM (McDaniel, Henderson, and Rathouz 2013), gee (Carey 2015) and geepack (Højsgaard, Halekoh, and Yan 2006). All of them are limited to deal with one response variable and the modeling of the covariance structure is currently restricted to making a selection from a short list of prespecified covariance structures, such as auto-regression or compound symmetry. In R, there are at least two GLMMs packages that can deal with multivariate response variables, namely MCMCglmm (Hadfield 2010), which uses Markov chain Monte Carlo methods in the Bayesian framework, and the package SabreR (Crouchley 2012), which uses marginal likelihood but is limited to dealing with at most three response variables.

In SAS the GLIMMIX procedure for GLMMs deals with multivariate response variables but is limited to the exponential family of distributions and a few pre-determined covariance structures (SAS Institute 2011). Other software platforms for fitting generic random-effects models via Markov chain Monte Carlo methods, such as JAGS (Plummer 2003) WinBUGS (Lunn, Thomas, Best, and Spiegelhalter 2000) and Stan (Carpenter, Gelman, Hoffman, Lee, Goodrich, Betancourt, Brubaker, Guo, Li, and Riddell 2017), can deal with multivariate response variables but carry substantial overheads in terms of computational times and convergence checks, while being cumbersome to implement non-standard covariance structures and more general probability distributions, such as the Tweedie and Poisson-Tweedie distributions. These limitations of current software availability for joint mean-covariance modeling of multivariate response variables motivated us to develop an implementation of McGLMs and consequently the mcglm package.

The main goal of this article is to describe the functionalities of the **mcglm** package for fitting multivariate covariance generalized linear models. Through six worked examples, we show the flexibility of the package to deal with different types of dependence structures, arising for example in mixed models, repeated measures and longitudinal data analysis, as well as in spatial areal data. By using the score information criterion, we discuss the selection of the linear and matrix linear predictor components. More challenging examples, as the cases of mixed outcomes (Bonat 2017), multivariate Poisson-Tweedie models for count data (Jørgensen and Kokonendji 2016; Bonat, Olivero, Grande-Vega, Fárfan, and Fa 2017) and multivariate Tweedie models (Jørgensen 2013; Jørgensen and Lauritzen 2000) for spatial areal data are also discussed.

The article is organized as follows. Section 2 introduces the multivariate covariance generalized linear models with emphasis to the specification of the matrix linear predictor. Section 3 presents the fitting algorithm based on the estimating function approach. Section 4 provides some measures of goodness-of-fit. In particular, we discuss the generalized error sum of squares (ESS), the pseudo Gaussian log-likelihood (plogLik) and its extensions, the pseudo Akaike information criterion (pAIC) and the Kullback-Leibler (pKLIC) information criterion. Furthermore, the score information criterion (SIC) is presented for the selection of the components of the linear and matrix linear predictors. Section 5 introduces the R implementation discussing the main functions and methods available in the mcglm package. Section 6 illus-

trates the package usage through six worked examples. Finally, Section 7 presents a discussion and directions for future work on the improvement of the **mcglm** package.

2. Multivariate covariance generalized linear models

Let $\mathbf{Y}_{N\times R} = \{\mathbf{Y}_1, \dots, \mathbf{Y}_R\}$ be an outcome matrix and let $\mathbf{M}_{N\times R} = \{\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_R\}$ denote the corresponding matrix of expected values. Let $\boldsymbol{\Sigma}_r$ denote the $N\times N$ covariance matrix within the outcome r for $r=1,\dots,R$. Similarly, let $\boldsymbol{\Sigma}_b$ be the $R\times R$ correlation matrix between outcomes. The McGLMs (Bonat and Jørgensen 2016) are defined by

$$\mathsf{E}(\mathbf{Y}) = \mathbf{M} = \{g_1^{-1}(m{X}_1m{eta}_1), \dots, g_R^{-1}(m{X}_Rm{eta}_R)\}$$
 $\mathsf{VAR}(\mathbf{Y}) = m{C} = m{\Sigma}_R \overset{G}{\otimes} m{\Sigma}_b$

where $\Sigma_R \overset{G}{\otimes} \Sigma_b = \operatorname{Bdiag}(\tilde{\Sigma}_1, \dots, \tilde{\Sigma}_R)(\Sigma_b \otimes I) \operatorname{Bdiag}(\tilde{\Sigma}_1^\top, \dots, \tilde{\Sigma}_R^\top)$ is the generalized Kronecker product (Martinez-Beneito 2013). The matrix $\tilde{\Sigma}_r$ denotes the lower triangular matrix of the Cholesky decomposition of Σ_r . The operator $\operatorname{Bdiag}()$ denotes a block diagonal matrix and I denotes an $N \times N$ identity matrix. The functions $g_r()$ are orthodox link functions. Let X_r denote an $N \times k_r$ design matrix and β_r a $k_r \times 1$ regression parameter vector. For continuous, binary, binomial, proportions or indexes the covariance matrix within outcomes Σ_r is defined by

$$\Sigma_r = V(\boldsymbol{\mu}_r; p_r)^{\frac{1}{2}} (\boldsymbol{\Omega}(\boldsymbol{\tau}_r)) V(\boldsymbol{\mu}_r; p_r)^{\frac{1}{2}}.$$

Similarly, for count data the covariance matrix within outcomes takes the following form

$$\Sigma_r = \operatorname{diag}(\boldsymbol{\mu}_r) + V(\boldsymbol{\mu}_r; p_r)^{\frac{1}{2}} (\Omega(\boldsymbol{\tau}_r)) V(\boldsymbol{\mu}_r; p_r)^{\frac{1}{2}}, \tag{1}$$

where $V(\mu_r; p_r) = \operatorname{diag}(\vartheta(\mu_r; p_r))$ denotes a diagonal matrix, whose main entries are given by the variance function $\vartheta(\cdot; p_r)$ applied element wise to the vector μ_r .

The variance function plays an important role in McGLMs, since different choices for $\vartheta(\cdot; p_r)$ imply different marginal outcome distributions. The **mcglm** package implements three set of variance functions. To deal with continuous outcomes the power variance function $\vartheta(\cdot; p_r) = \mu_r^{p_r}$ provides a flexible family of models, since it describes the Tweedie family of distributions that has as special cases the Gaussian (p=0), Gamma (p=2) and inverse Gaussian (p=3) distributions (Jørgensen 1987, 1997). For handling binary, binomial or proportional data the extended binomial variance function defined by $\vartheta(\cdot; p_r) = \mu_r^{p_{r1}} (1 - \mu_r)^{p_{r2}}$ may be used. Finally, for modeling count outcomes the **mcglm** package implements the Poisson-Tweedie dispersion function (Jørgensen and Kokonendji 2016), i.e., $\vartheta(\cdot; p) = \mu + \tau \mu^p$, where τ is the dispersion parameter. Note that, since the dispersion parameter appears only in the second term, the covariance within outcomes takes the special form in Equation 1. The Poisson-Tweedie family of distributions provides a rich class of models to deal with count outcomes, since many important distributions appear as special cases, examples include the Hermite (p=0), Neyman Type A (p=1), negative binomial (p=2) and Poisson-inverse Gaussian (p=3) distributions.

We highlight that the dispersion function introduced by Jørgensen and Kokonendji (2016) is not a variance function in the sense of Jørgensen (1997), however, for practical data analysis both are completely analogous. In this paper we adopt the term variance function for both for

simplicity. It is justified, since in general all features attributed to variance functions extend easily to dispersion functions in our framework.

The power parameter p is important in the context of McGLMs, since for all variance functions discussed it is an index which distinguishes between important distributions. The algorithm we shall present in Section 3 allows us to estimate the power parameter, which works as an automatic distribution selection. It is important to highlight that given the second-moment specification of McGLMs the estimation of the power parameters requires that the mean vector varies, i.e., requires the presence of significant covariates in the linear predictor. The information for estimation of the power parameter comes from the relationship between the mean and variance, thus an enough variation in the mean vector is necessary for estimation of the power parameter.

The dispersion matrix $\Omega(\tau_r)$ describes the part of the covariance within outcomes that does not depend on the mean structure. Based on the ideas of Anderson (1973) and Pourahmadi (2000), Bonat and Jørgensen (2016) proposed to model the dispersion matrix using a matrix linear predictor combined with a covariance link function, i.e.,

$$h(\mathbf{\Omega}(\boldsymbol{\tau}_r)) = \tau_{r0} Z_{r0} + \dots + \tau_{rD} Z_{rD}, \tag{2}$$

where h() is the covariance link function, Z_{rd} with d = 0, ..., D are known matrices reflecting the covariance structure within the response variable r, and $\tau_r = (\tau_{r0}, ..., \tau_{rD})$ is a $(D+1)\times 1$ parameter vector. The **mcglm** package implements three covariance link functions, namely, the identity, inverse and exponential-matrix (Chiu, Leonard, and Tsui 1996).

An important feature of the McGLMs framework is that, whereas the regression parameter estimators depend relatively little on the form of the covariance structure, this is not so for the standard errors of the regression parameter estimators, which depend directly on the choice of covariance structure.

McGLMs are defined by three functions, namely, link, variance and covariance functions and a linear predictor and a matrix linear predictor for each response variable. Thus, there is no loss of generality to discuss the specification of the matrix linear predictor for the one response variable case. Demidenko (2013) showed that the covariance structure induced by the orthodox Gaussian linear mixed model is a linear covariance matrix, i.e., has the form of Equation 2. In this sense, McGLMs can been seen as an extension of Gaussian linear mixed models for handling non-Gaussian data. Furthermore, popular approaches to deal with longitudinal auto-correlated data, as the compound symmetry, moving average and first order auto-regressive approaches, are also covariance linear models. In what follows we discuss some of the possibilities for the specification of the matrix linear predictor in the context of longitudinal and spatial data analysis.

Often in the context of longitudinal data analysis the outcomes are collected for a set of independent groups or unit samples at multiple follow-up times. Bonat et al. (2017) discussed the analysis of multivariate longitudinal count models using McGLMs and following their notation, denote y_{go} an observation $o = 1, ..., O_g$ within the group g = 1, ..., G and let y_g denote the O_g -dimensional vector of measurements from the gth group. The response variable vector is given by $\mathbf{Y} = (y_1, ..., y_G)^{\top}$. Let A_g denote an $O_g \times E$ design matrix composed of the values of E known covariates available to model the covariance structure. Furthermore, let $A_{g,e}$ denote the eth column of the matrix A_g . The main effect of the covariate e and the interaction effect between the covariates e and e' are included in the covariance model

through the symmetric matrices

$$A_q^e = A_{g,\cdot e} A_{q,\cdot e}^{\top}$$
 and $A_q^{ee'} = A_{g,\cdot e} A_{q,\cdot e'}^{\top} + A_{g,\cdot e'} A_{q,\cdot e}^{\top}$

respectively. The matrices A_g^e and $A_g^{ee'}$ are group specific. To obtain the components of the matrix linear predictor for the entire response variable vector \mathbf{Y} , we assume independent groups. Thus, the components of the matrix linear predictor that measure the effect of the eth covariate and the interaction effect are respectively given by

$$Z_e = \operatorname{Bdiag}(A_1^e, \dots, A_G^e) \quad \text{and} \quad Z_{ee'} = \operatorname{Bdiag}(A_1^{ee'}, \dots, A_G^{ee'}),$$
 (3)

where as before the operator Bdiag() denotes a block diagonal matrix. The matrices Z_e and $Z_{ee'}$ can be included as the Z_d 's components in the matrix linear predictor, see Equation 2. These structures can be combined with any of the three covariance link functions available in the **mcglm** package. In particular, the combination with the identity covariance link function provides a straightforward extension of Gaussian linear mixed models to deal with non-Gaussian data. Note that these simple structures provide a way to introduce the effects of continuous and categorical covariates in the covariance model in a linear mixed models fashion. These structures can be easily constructed in R using the function mc_mixed of the mcglm package.

The compound symmetry or exchangeable structure is a popular choice in the analysis of repeated measures data, it is defined by a linear combination of an identity and a matrix of ones, i.e., for a particular group with three observations the matrix linear predictor is given by

$$m{\Omega}_g(m{ au}) = au_0 egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{bmatrix} + au_1 egin{bmatrix} 1 & 1 & 1 \ 1 & 1 & 1 \ 1 & 1 & 1 \end{bmatrix}.$$

Note that, when the design matrix A_g contains the intercept, the first term $A_{g,\cdot 1}A_{g,\cdot 1}^{\top}$ corresponds to a matrix of ones, that combined with an identity matrix (mc_id) results in the compound symmetry model.

The moving average model of order p MA(p) is also a linear covariance model. The components of the matrix linear predictor associated with the MA(1) and MA(2) structures are given respectively by

$$A_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad \text{and} \quad A_2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix},$$

the components of these models can be created in R using the function mc_ma of the mcglm package. For longitudinal data analysis, we can use the inverse of the Euclidean distance or any other measure of distance between pairs of observations as a component of the matrix linear predictor, for example

$$A_1 = \begin{bmatrix} 0 & 1/d_{12} & 1/d_{13} \\ 1/d_{12} & 0 & 1/d_{23} \\ 1/d_{13} & 1/d_{23} & 0 \end{bmatrix},$$

where d_{ij} denotes the distance between the observations at time i and j. See, for example the function mc_dist for more details.

In the Bayesian context Gaussian Markov random fields (GMRF; Rue and Held 2005) are often employed for the analysis of times series and areal data. These models specify the precision matrix (i.e., the inverse of the covariance matrix) in the following way

$$\Omega_r^{-1}(\tau_0, \rho) = \tau(\mathbf{D} - \rho \mathbf{W}), \tag{4}$$

where W is a neighborhood matrix and D is a diagonal matrix with the number of neighbors in the main diagonal. The model is parameterized by the precision τ and auto-correlation parameter ρ . The matrices D and W can model space, time and space-time interaction in a straightforward way, by using different neighborhood matrices. It is easy to see, that the model in Equation 4 is a linear covariance model using the inverse covariance link function, i.e.,

$$\mathbf{\Omega}_r^{-1}(\boldsymbol{\tau}) = \tau_0 \boldsymbol{D} + \tau_1 \boldsymbol{W},$$

where $\tau_0 = \tau$ and $\tau_1 = -\tau \rho$. In the Bayesian context, it is common to fix the auto-correlation parameter ρ at the value 1, which is the so-called intrinsic conditional auto-regressive model. For times series and longitudinal data the neighborhood structure is naturally specified by the time structure. For spatial data the function tri2nb of the spdep package (Bivand and Piras 2015; Bivand 2017) can be used to create the neighborhood matrix based on a vector of spatial coordinates. The functions mc_rw and mc_car provided by the mcglm package help to build the components of the matrix linear predictor associated with these models. Furthermore, the structures can be combined to deal with space-temporal data, see Bonat and Jørgensen (2016, Example 3).

Some additional fields for application of McGLMs include additive genetic models. Hadfield and Nakagawa (2010) showed that virtually all models used in the fields of quantitative genetic and phylogenetic in the Gaussian case are special specifications of the matrix linear predictor involving different types of known matrices, such as the additive genetic relatedness matrix. Examples include the phylogenetic meta-analysis, the taxonomic mixed model and the traditional animal models. In that case, the R package **nadiv** (Wolak 2012) can be useful for creating the components of the matrix linear predictor associated with these models. Furthermore, these components can easily be incorporated in the **mcglm** package, as for example in Bonat (2017). The analysis of twin and family data can be done and extended by a suitable specification of the matrix linear predictor (Rabe-Hesketh, Skrondal, and Gjessing 2008).

3. Estimation and inference

McGLMs are fitted based on the estimating function approach described in detail by Bonat and Jørgensen (2016) and Jørgensen and Knudsen (2004). In this section we present a general overview of the algorithm and the asymptotic distribution of the estimating function estimators. The second-moment assumptions of McGLMs motivate us to divide the set of parameters into two subsets $\boldsymbol{\theta} = (\boldsymbol{\beta}^{\top}, \boldsymbol{\lambda}^{\top})^{\top}$. In this notation $\boldsymbol{\beta} = (\boldsymbol{\beta}_1^{\top}, \dots, \boldsymbol{\beta}_R^{\top})^{\top}$ and $\boldsymbol{\lambda} = (\rho_1, \dots, \rho_{R(R-1)/2}, p_1, \dots, p_R, \boldsymbol{\tau}_1^{\top}, \dots, \boldsymbol{\tau}_R^{\top})^{\top}$ denote a $K \times 1$ and $Q \times 1$ vector of all regression and dispersion parameters, respectively.

Let $\mathcal{Y} = (\mathbf{Y}_1^\top, \dots, \mathbf{Y}_R^\top)^\top$ and $\mathcal{M} = (\boldsymbol{\mu}_1^\top, \dots, \boldsymbol{\mu}_R^\top)^\top$ denote the $NR \times 1$ stacked vector of the response variable matrix $\mathbf{Y}_{N \times R}$ and expected values matrix $\mathbf{M}_{N \times R}$ by columns, respectively.

The quasi-score function (Liang and Zeger 1986) was adopted for the regression parameters

$$\psi_{\beta}(\beta, \lambda) = \boldsymbol{D}^{\top} \boldsymbol{C}^{-1} (\boldsymbol{\mathcal{Y}} - \boldsymbol{\mathcal{M}}),$$

where $\mathbf{D} = \nabla_{\beta} \mathcal{M}$ is an $NR \times K$ matrix, and ∇_{β} denotes the gradient operator. The $K \times K$ sensitivity and variability matrices of ψ_{β} are respectively given by

$$S_{\beta} = E(\nabla_{\beta}\psi_{\beta}) = -\mathbf{D}^{\top}\mathbf{C}^{-1}\mathbf{D}$$
 and $V_{\beta} = VAR(\psi_{\beta}) = \mathbf{D}^{\top}\mathbf{C}^{-1}\mathbf{D}$.

The Pearson estimating function, defined by the components

$$\psi_{\lambda_i}(\boldsymbol{\beta}, \boldsymbol{\lambda}) = \operatorname{tr}(W_{\lambda_i}(\boldsymbol{r}^{\top} \boldsymbol{r} - \boldsymbol{C})) \text{ for } i = 1, \dots, Q,$$

where $W_{\lambda_i} = -\partial \mathbf{C}^{-1}/\partial \lambda_i$ and $\mathbf{r} = \mathcal{Y} - \mathcal{M}$, was adopted for the dispersion parameters. The entry (i, j) of the $Q \times Q$ sensitivity matrix of ψ_{λ} is given by,

$$\mathbf{S}_{\lambda_{ij}} = \mathsf{E}\left(\frac{\partial}{\partial \lambda_i} \psi_{\lambda_j}\right) = -\mathrm{tr}\left(W_{\lambda_i} C W_{\lambda_j} C\right).$$

The entry (i,j) of the $Q \times Q$ variability matrix of ψ_{λ} is given by

$$V_{\boldsymbol{\lambda}_{ij}} = \text{Cov}(\psi_{\boldsymbol{\lambda}_i}, \psi_{\boldsymbol{\lambda}_j}) = 2\text{tr}(W_{\boldsymbol{\lambda}_i} \boldsymbol{C} W_{\boldsymbol{\lambda}_j} \boldsymbol{C}) + \sum_{l=1}^{NR} k_l^{(4)} (W_{\boldsymbol{\lambda}_i})_{ll} (W_{\boldsymbol{\lambda}_j})_{ll},$$

where $k_l^{(4)}$ denotes the fourth cumulant of \mathcal{Y}_l , for which we use the empirical version.

To take into account the covariance between the vectors $\boldsymbol{\beta}$ and $\boldsymbol{\lambda}$, Bonat and Jørgensen (2016) computed the *cross-sensitivity* and *cross-variability* matrices. Denote these quantities by $S_{\lambda\beta}$, $S_{\beta\lambda}$ and $V_{\lambda\beta}$, respectively. For details see Bonat and Jørgensen (2016, Section 3).

The joint sensitivity and variability matrices of ψ_{β} and ψ_{λ} are given by

$$S_{\theta} = \begin{pmatrix} S_{\beta} & S_{\beta\lambda} \\ S_{\lambda\beta} & S_{\lambda} \end{pmatrix}$$
 and $V_{\theta} = \begin{pmatrix} V_{\beta} & V_{\lambda\beta}^{\top} \\ V_{\lambda\beta} & V_{\lambda} \end{pmatrix}$.

Let $\hat{\boldsymbol{\theta}} = (\hat{\boldsymbol{\beta}}^\top, \hat{\boldsymbol{\lambda}}^\top)^\top$ be the estimating function estimator of $\boldsymbol{\theta}$. Then the asymptotic distribution of $\hat{\boldsymbol{\theta}}$ is

$$\hat{\boldsymbol{\theta}} \sim \mathrm{N}(\boldsymbol{\theta}, \mathrm{J}_{\boldsymbol{\theta}}^{-1}),$$

where J_{θ}^{-1} is the inverse of the Godambe information matrix,

$$J_{\boldsymbol{\theta}}^{-1} = S_{\boldsymbol{\theta}}^{-1} V_{\boldsymbol{\theta}} S_{\boldsymbol{\theta}}^{-\top},$$

where $S_{\boldsymbol{\theta}}^{-\top} = (S_{\boldsymbol{\theta}}^{-1})^{\top}$.

The modified chaser algorithm proposed by Jørgensen and Knudsen (2004) is employed to solve the system of equations $\psi_{\beta} = \mathbf{0}$ and $\psi_{\lambda} = \mathbf{0}$, defined by

$$\boldsymbol{\beta}^{(i+1)} = \boldsymbol{\beta}^{(i)} - S_{\boldsymbol{\beta}}^{-1} \psi_{\boldsymbol{\beta}}(\boldsymbol{\beta}^{(i)}, \boldsymbol{\lambda}^{(i)}),$$

$$\boldsymbol{\lambda}^{(i+1)} = \boldsymbol{\lambda}^{(i)} - \alpha S_{\boldsymbol{\lambda}}^{-1} \psi_{\boldsymbol{\lambda}}(\boldsymbol{\beta}^{(i+1)}, \boldsymbol{\lambda}^{(i)}).$$
 (5)

In the **mcglm** package, we introduce the extra tuning constant α to control the step length. Note that the modified chaser algorithm uses the insensitivity property (Jørgensen and Knudsen 2004), which allows us to use two separate equations to update β and λ . Bonat and Jørgensen (2016) also proposed the reciprocal likelihood algorithm that replaces the second equation in Equation 5 by

$$\boldsymbol{\lambda}^{(i+1)} = \boldsymbol{\lambda}^{(i)} - [\alpha \psi_{\boldsymbol{\lambda}}(\boldsymbol{\beta}^{(i+1)}, \boldsymbol{\lambda}^{(i)})^{\top} \psi_{\boldsymbol{\lambda}}(\boldsymbol{\beta}^{(i+1)}, \boldsymbol{\lambda}^{(i)}) V_{\boldsymbol{\lambda}}^{-1} S_{\boldsymbol{\lambda}} + S_{\boldsymbol{\lambda}}]^{-1} \psi_{\boldsymbol{\lambda}}(\boldsymbol{\beta}^{(i+1)}, \boldsymbol{\lambda}^{(i)}),$$

where again we introduce the tuning constant α to control the step length. The **mcglm** package implements both the modified chaser and reciprocal likelihood algorithms as well as allows the user to control the step length through the argument alpha (see Section 5). The **mcglm** package also implements the bias-correction term proposed by Jørgensen and Knudsen (2004). Details about how to compute the derivatives in the weight matrices required in the Pearson estimating function can be found in Bonat and Jørgensen (2016).

4. Measures of goodness-of-fit

Model selection is an important issue in almost any practical data analysis. A common problem is variable selection in regression: given a large group of covariates (including some higher order terms), one needs to select a subset to be included in the regression model. To face this problem, Stoklosa, Gibb, and Warton (2014) in the context of generalized estimating equations (GEE) proposed the score information criterion (SIC) to be used with forward selection algorithms in the cases where we have a large number of covariates to compose the linear predictor. Bonat et al. (2017) extended the SIC to select the components of the matrix linear predictor. The SIC is based on the score statistics. This makes the use of this criterion convenient, since it can be computed for all candidate models without actually fitting them. In this section, we describe the SIC with the emphasis placed on the selection of the components of the matrix linear predictor. It is straightforward to apply the same arguments for the selection of the components of the linear predictor.

Suppose without loss of generality that r=1 and that the power parameter is fixed. In that case, the vector of dispersion parameters simplifies to $\lambda = \tau$. For a given mean structure, suppose that the parameter vector $\boldsymbol{\tau}$ can be partitioned as $\boldsymbol{\tau} = (\boldsymbol{\tau}_1^\top, \boldsymbol{\tau}_2^\top)^\top$, whose dimensions are $(Q-s)\times 1$ and $s\times 1$, respectively. The Pearson estimating function ψ_{λ} and its sensitivity and variability matrices, can also be partitioned to $\psi_{\lambda}(\boldsymbol{\beta}, \boldsymbol{\tau}) = (\psi_{\lambda_1}(\boldsymbol{\beta}, \boldsymbol{\tau}_1)^\top, \psi_{\lambda_2}(\boldsymbol{\beta}, \boldsymbol{\tau}_2)^\top)^\top$,

$$S_{\pmb{\lambda}} = \begin{pmatrix} S_{\pmb{\lambda}_{11}} & S_{\pmb{\lambda}_{12}} \\ S_{\pmb{\lambda}_{21}} & S_{\pmb{\lambda}_{22}} \end{pmatrix} \quad \text{and} \quad V_{\pmb{\lambda}} = \begin{pmatrix} V_{\pmb{\lambda}_{11}} & V_{\pmb{\lambda}_{12}} \\ V_{\pmb{\lambda}_{21}} & V_{\pmb{\lambda}_{22}} \end{pmatrix},$$

respectively. The null hypothesis H_0 is $\boldsymbol{\tau}_2 = \mathbf{0}$. Let $\tilde{\boldsymbol{\tau}} = (\hat{\boldsymbol{\tau}}_1^\top, \mathbf{0}^\top)^\top$ be the vector of Pearson estimates under H_0 . Note that only the base model containing $\hat{\boldsymbol{\tau}}_1$ parameters has to be fitted. In practical situations, this model can contain only a simple intercept. The Pearson estimating function takes the form

$$\psi_{\lambda}(\beta, \tilde{\boldsymbol{\tau}}) = (\psi_{\lambda_1}^{\top}(\beta, \tilde{\boldsymbol{\tau}}), \psi_{\lambda_2}^{\top}(\beta, \tilde{\boldsymbol{\tau}}))^{\top} = (\mathbf{0}^{\top}, \psi_{\lambda_2}^{\top}(\beta, \tilde{\boldsymbol{\tau}}))^{\top}.$$

The generalized score statistic is given by

$$T_{\lambda_2}(\boldsymbol{\beta}, \tilde{\boldsymbol{\tau}}) = \psi_{\lambda_2}^{\top}(\boldsymbol{\beta}, \tilde{\boldsymbol{\tau}}) \mathsf{VAR}(\psi_{\lambda_2}(\boldsymbol{\beta}, \tilde{\boldsymbol{\tau}}))^{-1} \psi_{\lambda_2}(\boldsymbol{\beta}, \tilde{\boldsymbol{\tau}}), \tag{6}$$

where

$$\mathsf{VAR}(\psi_{\lambda_2}(\beta, \tilde{\tau})) = V_{\lambda_{22}} - S_{\lambda_{21}} S_{\lambda_{11}}^{-1} V_{\lambda_{12}} - V_{\lambda_{12}} S_{\lambda_{11}}^{-1} S_{\lambda_{12}} + S_{\lambda_{21}} S_{\lambda_{11}}^{-1} V_{\lambda_{11}} S_{\lambda_{12}}^{-1} S_{\lambda_{12}}$$

is the variance of the sub-vector $\psi_{\lambda_2}(\beta, \tilde{\tau})$. Under the null hypothesis, $T_{\lambda_2}(\beta, \tilde{\tau})$ has a chisquare distribution with s degrees of freedom. In practice, all quantities in Equation 6 are
evaluated at the Pearson estimates under the null hypothesis. If H_0 were true, then $\psi_{\lambda_2}(\beta, \tilde{\tau})$,
that is the Pearson estimating function for τ_2 , would be close to zero when evaluated under
the null. Large values of $T_{\lambda_2}(\beta, \tilde{\tau})$ would argue against H_0 . The main idea behind the SIC is
to use Equation 6 as a quadratic approximation to the log-likelihood ratio statistic. The SIC
is defined by

$$\mathrm{SIC}^{(1)}(\boldsymbol{\beta}, \boldsymbol{\tau}) = -T_{\lambda_2}(\boldsymbol{\beta}, \tilde{\boldsymbol{\tau}}) + \delta |\boldsymbol{\tau}|.$$

Note that this criterion is a function of $\tilde{\tau}$ only, thus only the base model needs to be fitted. The SIC can be combined with the Wald statistic in a stepwise procedure, as described in Bonat et al. (2017). The **mcglm** package implements the SIC for selection of the linear and matrix linear predictors components, by the functions mc_sic and mc_sic_covariance. The user can use the penalty $\delta=2$, as it is analogous to the Akaike information criterion. It is also possible to use $\delta=\log(N)$ to have an analogous to the Bayesian information criterion or any other penalty specified by the user.

The SIC is an important tool to assist with the selection of the linear and matrix linear predictors components, but it is less useful for comparing models fitted using different link, variance or covariance functions. Furthermore, the application of the SIC to compare nonnested models can be difficult, because of the requirement to have a base model for comparison. Thus, it is useful to have measures of goodness-of-fit similar to the *Akaike* information criterion in the context of likelihood analysis.

Carey and Wang (2011) proposed the Gaussian pseudo log-likelihood (plogLik) given by

$$\operatorname{plogLik}(\boldsymbol{\theta}) = -\frac{NR}{2} \log(2\pi) - \frac{1}{2} \log|\hat{\boldsymbol{C}}| - (\boldsymbol{\mathcal{Y}} - \hat{\boldsymbol{\mathcal{M}}})^{\top} \hat{\boldsymbol{C}}^{-1} (\boldsymbol{\mathcal{Y}} - \hat{\boldsymbol{\mathcal{M}}}),$$

where NR is the total number of observations, $\hat{\mathcal{M}}$ and $\hat{\mathbf{C}}$ denote the estimated vector of expected values and covariance matrix, respectively.

We combined three penalty terms with the Gaussian pseudo log-likelihood in order to have analogs to the Akaike, Bayesian and Kullback-Leibler information criterion. Thus, the pseudo Akaike information criterion (pAIC) is given by

$$pAIC(\boldsymbol{\theta}) = 2(P+Q) - 2plogLik(\boldsymbol{\theta}),$$

where P is the number of regression parameters, and Q is the number of dispersion parameters. Similarly, the pseudo Bayesian information criterion (pBIC) is obtained by

$$pBIC(\boldsymbol{\theta}) = \log NR(P+Q) - 2p\log Lik(\boldsymbol{\theta}).$$

Finally, the pseudo Kullback-Leibler information criterion (pKLIC) is given by

$$pKLIC(\boldsymbol{\theta}) = 2tr(S_{\boldsymbol{\theta}}^{-1}V_{\boldsymbol{\theta}}) - 2plogLik(\boldsymbol{\theta}),$$

where S_{θ} and V_{θ} are the joint sensitivity and variability matrices defined in Section 3. These measures of goodness-of-fit are implemented in the **mcglm** package and can be accessed together using the function gof or individually by the functions indicated in brackets.

5. Implementation in R

The main function of the **mcglm** package is mcglm() which allows to fit multivariate covariance generalized linear models using quasi-score and Pearson estimating functions. The synopsis of the mcglm() function is:

```
mcglm(linear_pred, matrix_pred, link, variance, covariance, offset, Ntrial,
   power_fixed, data, control_initial = "automatic", contrasts = NULL,
   control_algorithm = list())
```

The argument linear_pred specifies the linear predictor for each response variable using a list of 'formula' objects. For example, in a bivariate case with response variables y1 and y2 and a covariate x1, the linear_pred argument is specified as linear_pred = $c(y1 \sim x1, y2 \sim x1)$. Similarly, the argument matrix_pred specifies the matrix linear predictor for each response variable, but now using a list of known matrices. The mcglm package provides some pre-specified covariance structures (see Section 2), but the users can use any symmetric matrix as a component of the matrix linear predictor. Consider a simple longitudinal structure with two unit samples (id) and two replications (time) as follows:

```
R > data <- data.frame("id" = gl(2, 2), "time" = rep(1:2, 2))
```

The components of the matrix linear predictor, for example, for a moving average first order model MA(1) are given by:

```
R > Z0 <- mc_id(data)

R > Z1 <- mc_ma(id = "id", time = "time", data = data, order = 1)
```

In this way, for the bivariate case considered above the matrix_pred argument is specified by:

```
R> matrix\_pred <- list(c(Z0, Z1), c(Z0, Z1))
```

The arguments link, variance and covariance specify, respectively, the link, variance and covariance link functions, for each response variable. The following link functions are implemented in the mcglm package: "logit", "probit", "cauchit", "cloglog", "loglog", "identity", "log", "sqrt" and "inverse". For the variance functions the options are: "constant", "tweedie", "binomialP", "binomialPQ" and "poisson_tweedie". Finally, the mcglm package implements three covariance link functions, namely, "identity", "inverse" and "expm" (exponential-matrix). For the bivariate case under consideration, the specification can be as follows:

```
R> link <- c("log", "logit")
R> variance <- c("poisson_tweedie", "binomialP")
R> covariance <- c("identity", "inverse")</pre>
```

In that case, we are using for the first response variable the logarithm, Poisson-Tweedie and identity functions as the link, variance and covariance functions. Similarly, for the second response variable the logit, binomial and inverse are the link, variance and covariance functions. This specification is suitable, for example, for the mix of count and binomial outcomes.

Functions	Description
print()	Simple printed display of model features.
<pre>summary()</pre>	Standard regression output.
fitted()	Fitted values for observed data.
residuals()	Pearson, raw and standardized residuals.
coef()	Coefficient estimates.
vcov()	Variance-covariance matrix of coefficient estimates.
<pre>confint()</pre>	Confidence intervals.
anova()	Analysis of variance tables for fitted models.
plot()	Diagnostic plots of Pearson residuals and algorithm check.

Table 1: Methods available for objects of class 'mcglm'.

The users can specify an offset for continuous or count data as well as the number of trials for binomial data through the arguments offset and Ntrial, respectively. In our bivariate case, suppose we have an offset available for the count response variable and also the number of trials for the binomial response variable. The specification of the arguments offset and Ntrial should be as follows:

```
R> Ntrial <- list(NULL, data$Ntrial)
R> offset <- list(data$offset, NULL)</pre>
```

For variance functions that depend on a power parameter, the users can either fix it using power_fixed = TRUE or estimate it using power_fixed = FALSE. For more than one response variable the usage extends easily to power_fixed = c(TRUE, FALSE), where we fix the power parameter for the first response variable while estimating it for the second one. The value of the power parameter is fixed at the initial value supplied to the argument control_initial. If no initial values are supplied the function mc_initial_values is called. For the power parameters the automatic initial values are 1 for all variance functions. For more details, see ?mc_initial_values. The data set is supplied through the argument data. The argument contrast is passed to the model.matrix function for specifying different contrasts for categorical covariates.

The argument control_algorithm should be a named list controlling features of the fitting algorithm. The options are: correct, a logical indicating if the corrected Pearson estimating function should be used; max_iter, the maximum number of iterations; tol, the convergence tolerance; method, a string indicating which algorithm should be used, i.e., modified chaser ("chaser") or reciprocal likelihood ("rc"). The tuning constant is specified by the option tuning. This should in general be a number smaller than 1. Finally, the logical verbose specifies if the trace of the algorithm iterations should be printed.

The returned fitted model object of class 'mcglm' is a list that contains, among others, the estimating function estimates, the sensitivity and the variability matrices. A set of standard methods is available to extract information from the fitted model, see Table 5. Most of the functions and methods use a standard syntax as implemented in other R packages oriented towards regression analysis.

The **mcglm** package implements some extra features and facilities useful for data analysis. For repeated measures and longitudinal data analysis the bias-corrected and robust standard

errors for regression parameters presented by Nuamah, Qu, and Amini (1996) are available through the functions mc_bias_corrected_std and mc_robust_std. The measures of goodness-of-fit discussed in Section 4 are available in the function gof. The selection of the components of linear and matrix linear predictors can be done using the functions mc_sic and mc_sic_covariance. Finally, conditional hypothesis tests can be performed with the function mc_conditional_test.

6. Examples

In this section, the usage of the **mcglm** package is illustrated with six worked examples covering various forms of dependent and multivariate data frequently arising in real applications.

6.1. Gaussian mixed models

The first example corresponds to Gaussian mixed models. We use the sleepstudy data set available in the lme4 package. The data set contains the average reaction time per day for subjects in a sleep deprivation study. On day 0 the subjects had their normal amount of sleep. Starting that night they were restricted to three hours of sleep per night. The response variable is the average reaction time on a series of tests given each day to each subject. The analysis goal is to understand how sleep deprivation affects the average reaction times. The dependence structure is introduced by observations taken for the same subject (repeated measures) and on sequential days (longitudinal). The analysis using the lme4 package is given by:

```
R> library("lme4")
R> data("sleepstudy", package = "lme4")
R> fit1.lme4 <- lmer(Reaction ~ Days + (Days | Subject), sleepstudy,
+ REML = FALSE)</pre>
```

Note that the fitted model has random intercepts and slopes associated with the covariate Days. The argument REML = FALSE indicates that we are using the maximum likelihood method instead of the restricted maximum likelihood method for estimation.

The marginal specification of this model can be fitted by the **mcglm** package. The first step is to specify the linear predictor.

```
R> form_ex1 <- Reaction ~ Days</pre>
```

The second step corresponds to building the components of the matrix linear predictor. Note that in that case we have to take into account the repeated measures effect (subject) as well as the effect of the covariate Days and perhaps the interaction term (correlation between the random intercept and slope) in a mixed models fashion, see Equation 3. The components of the matrix linear predictor are obtained by:

```
R> library("mcglm")
R> Z_ex1 <- mc_mixed(~ 0 + Subject / Days, data = sleepstudy)</pre>
```

We also include an intercept matrix corresponding to the residual variance.

```
R> Z0_ex1 <- mc_id(sleepstudy)</pre>
```

Finally, we fit the model.

In order to have estimates comparable with the ones obtained by the **lme4** package we are using the option <code>correct = FALSE</code> that corresponds in the Gaussian case to the maximum likelihood method.

```
R> summary(fit_ex1)
```

Call: Reaction ~ Days

Link function: identity
Variance function: constant
Covariance function: identity

Regression:

Estimates Std.error Z value (Intercept) 251.40510 6.632277 37.9063 Days 10.46729 1.502237 6.9678

Dispersion:

Estimates Std.error Z value 1 654.94103 70.62388 9.2736486 2 565.51537 264.67950 2.1366044 3 32.68220 13.55974 2.4102375 4 11.05543 42.94762 0.2574166

Algorithm: chaser Correction: FALSE Number iterations: 3

The summary() output presents the formula of the linear predictor, the link, the variance and the covariance functions specified for fitting the model. The parameter estimates are presented in two separate sets, Regression and Dispersion, with their associated standard errors and Z statistics. Finally, the fitting algorithm, if the bias correction term was used or not and the number of iterations required to reach convergence are shown.

We can compare the results obtained by the **mcglm** and **lme4** packages using the maximized value of the log-likelihood function.

```
R> logLik(fit1.lme4)
'log Lik.' -875.9697 (df=6)
R> plogLik(fit_ex1)
```

```
Pseudo log Lik. -875.97 (df=6)
```

The two packages provide virtually the same estimates for regression and dispersion parameters. However, the standard errors associated with the dispersion parameters (variance components) from the **mcglm** package are in general larger than the ones obtained by the **lme4** package. This is due to the robust specification of McGLMs and the use of a not fully efficient estimating function for estimation of the dispersion parameters. The interested reader can obtain these quantities using the **coef** function.

We now turn to the selection of the matrix linear predictor components using the SIC as presented in Section 4. In this case, we have four components to compose the matrix linear predictor. The initial or basic model can be the one assuming independent observations:

```
R> fit0_ex1 <- mcglm(linear_pred = c(form_ex1),
+ matrix_pred = list(resp = c(Z0_ex1)),
+ control_algorithm = list(correct = FALSE), data = sleepstudy)</pre>
```

The components of the matrix linear predictor associated with the two main effects are obtained by:

```
R > Z.sic \leftarrow list("Z1" = Z_ex1[[1]], "Z2" = Z_ex1[[2]])
```

Computing the SIC for these components is performed by:

SIC df df total

1 7.938022

The SIC values indicate that both components should be included in the model (SIC < 0). Thus,

4 0.06197811 3.841459

```
The SIC shows that the interaction effect is not required, which agrees with the first fitted model (fit_ex1) where the interaction effect is not significant.
```

Chisq

6.2. Longitudinal data analysis

The second example regards a fairly common longitudinal data analysis. We use the dietox data set available in package geepack. The analysis goal is to investigate the effect of dietary copper (Cu) and vitamin E (Evit) in diets containing 6% rapeseed oil on the performance status of growing pigs. In this application, for composing the linear predictor we have three covariates Evit, Cu and Time. We consider interaction terms up to the second order between the three main effects. In order to select the components of the linear predictor we are going to use the SIC. The longitudinal or repeated measures structure is introduced by the observations taken for the same animal. Thus, the matrix linear predictor is composed of an identity matrix combined with a compound symmetry structure, see Section 2.

```
R> data("dietox", package = "geepack")
R> Z0_ex2 <- mc_id(dietox)
R> Z1_ex2 <- mc_mixed(~ 0 + Pig, data = dietox)</pre>
```

To start the selection of the components of the linear predictor, we fit a simple intercept model, but also consider the repeated measures structure.

The candidate terms to enter into the linear predictor are:

```
R> scope <- c("poly(Time, 2)", "Evit", "Cu", "Evit * poly(Time, 2)", + "Cu * poly(Time, 2)", "Evit * Cu")
```

Now, we compute the SIC for all candidate terms. In that case, we decide to use the penalty log(N) to have an analog to the Bayesian information criterion.

```
SIC
                        Covariates df df total
                                                         Tu
                                                                Chisq
1 -687.30632
                     poly(Time, 2)
                                    2
                                              3 707.318622
                                                             5.991465
2
    17.17333
                              Evit
                                     2
                                              3
                                                  2.838969
                                                             5.991465
                                     2
    17.96460
                                Cu
                                              3
                                                   2.047695
                                                             5.991465
4 - 650.74637 Evit * poly(Time, 2)
                                     8
                                              9 710.783268 15.507313
5 -649.52533
               Cu * poly(Time, 2)
                                     8
                                              9 709.562228 15.507313
    54.68074
                         Evit * Cu
                                                   5.356152 15.507313
```

Clearly, the first term to be included in the model is the one associated with the Time trend.

```
R> fit1_ex2 <- mcglm(linear_pred = c(Weight ~ poly(Time, 2)),
+ matrix_pred = list(resp = c(Z0_ex2, Z1_ex2)), data = dietox)</pre>
```

Updating the candidate terms and computing the SIC are performed using:

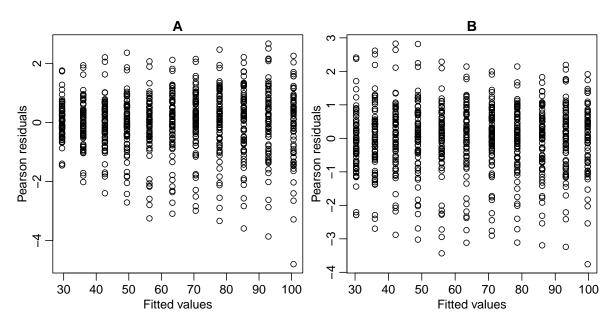


Figure 1: Pearson residuals against fitted values for models using constant (A) and Tweedie (B) variance functions.

```
R> scope <- c("Evit", "Cu", "Evit * poly(Time, 2)", "Cu * poly(Time, 2)",
     "Evit * Cu")
R> mc_sic(fit1_ex2, scope = scope, data = dietox, response = 1,
     penalty = log(N)
       SIC
                      Covariates df df_total
                                                       Tu
                                                              Chisq
1 30.21801
                             Evit
                                   2
                                             5
                                                3.135819
                                                           5.991465
2 31.12764
                                   2
                                                2.226191
                                                           5.991465
                               Cu
                                             5
3 39.70085 \text{ Evit } * \text{poly(Time, 2)}
                                   6
                                             9 20.336051 12.591587
4 53.96472
             Cu * poly(Time, 2)
                                                6.072174 12.591587
                                   6
5 67.59189
                       Evit * Cu
                                                5.786537 15.507313
                                            11
```

The SIC values show that the other terms are not required. Thus, we reached the final model. Figure 1(A) hints at the presence of variance heterogeneity. It indicates that a more general variance function, such as the Tweedie variance function can provide a better fit.

```
R> fit2_ex2 <- mcglm(linear_pred = c(Weight ~ poly(Time, 2)),
+ link = "log", variance = "tweedie", power_fixed = FALSE,
+ control_algorithm = list(tuning = 0.85),
+ matrix_pred = list(resp = c(Z0_ex2, Z1_ex2)), data = dietox)</pre>
```

The results in Figure 1(B) show that the tweedie variance function eases the variance heterogeneity detected in Figure 1(A). We can also use the measures of goodness-of-fit to decide about the best fit.

```
R> rbind(gof(fit1_ex2), gof(fit2_ex2))
```

```
plogLik Df pAIC pKLIC pBIC
1 -2134.58 5 4279.16 4387.053 4302.514
2 -2041.61 6 4095.22 4214.939 4123.245
```

The measures of goodness-of-fit employed show that the model using the "tweedie" variance function provides the best fit for the dietox data set. In general the estimation of the power parameter inflates the standard errors associated with the dispersion parameter estimates. Thus, we suggest to use a conditional hypothesis test where the value of the power parameter is fixed at its estimate instead of the orthodox marginal test. For the dietox data the results of the marginal test for the dispersion parameter estimates associated with the repeated measures structure indicate that this effect is not significant. On the other hand, the conditional test shows that the repeated measures effect is significant as expected. The marginal test is obtained using:

6.3. Spatial areal data analysis

This example regards the malaria prevalence in children recorded at 65 villages in Gambia. We follow Masarotto and Varin (2017) who consider the aggregated data at village level. The data set is available in the **gcmr** package. The response variable is the number of sampled children with malaria in each village. Possible covariates include the frequency of sampled children who regularly sleep under a bed-net in each village (netuse). A measure of vegetation greenness in the immediate vicinity of the village (green) and an indicator variable denoting the presence or absence of a health center in the village (phd). Following Masarotto and Varin (2017) we specify the following linear predictor using:

```
R> library("spdep")
R> data("malaria", package = "gcmr")
R> malaria$Y <- malaria$cases / malaria$size
R> form_ex3 <- Y ~ netuse + I(green / 100) + phc</pre>
```

In this example the response variable is binomial, thus we first compute the proportion of children with malaria in each village. To model the spatial effect, we apply the conditional auto-regressive model, see Equation 4.

```
R> list_neigh <- tri2nb(coords = malaria[, 1:2])
R> Z_ex3 <- mc_car(list_neigh = list_neigh)</pre>
```

The following call of the mcglm function fits the spatial model. This model is then summarized:

```
R> fit1_ex3 <- mcglm(linear_pred = c(form_ex3), matrix_pred = list(Z_ex3),
     link = "logit", variance = "binomialP", covariance = "inverse",
     control_algorithm = list(verbose = FALSE, max_iter = 100,
       tuning = 0.1, method = "rc"), Ntrial = list(malaria$size),
     data = malaria)
R> summary(fit1_ex3)
Call: Y ~ netuse + I(green / 100) + phc
Link function: logit
Variance function: binomialP
Covariance function: inverse
Regression:
                Estimates Std.error
                                      Z value
(Intercept)
               -1.2974098 0.9301458 -1.394846
netuse
               -0.9862835 0.2909367 -3.390028
I(green / 100) 3.2369222 1.7879445 1.810415
```

-0.3449150 0.1827457 -1.887404

Dispersion:

phc

```
Estimates Std.error Z value
1 0.05421655 0.01018959 5.320778
2 0.04141227 0.01448750 2.858483
```

Algorithm: rc Correction: TRUE Number iterations: 23

Note that in this example we are using the reciprocal likelihood algorithm (method = "rc") and the tuning constant (tuning = 0.1). Since, we have a binomial response variable, we specify the logit and binomialP as the link and variance functions, respectively. Finally, to obtain the conditional auto-regressive model we are using the inverse covariance link function. Concerning the covariate effects only the covariate netuse shows a significant effect. The components of the matrix linear predictor show a significant spatial effect. The function mc_compute rho computes the spatial auto-correlation estimates based on a fitted model.

An alternative model is obtained by using the inverse of the Euclidean distance combined with the exponential-matrix covariance link function.

We compare the fitted models using the measures of goodness-of fit presented in Section 4.

```
R> rbind(gof(fit1_ex3), gof(fit2_ex3))

plogLik Df pAIC pKLIC pBIC
1 23.64 6 -35.28 -31.03616 -22.23368
2 23.84 6 -35.68 -34.19290 -22.63368
```

In that case, the model using the inverse of the Euclidean distance and the expm covariance link function provides a fit slightly better than the conditional auto-regressive model.

6.4. Mixed response variables

The experiment analyzed in this section was carried out in a vegetation house with soybeans. The experiment has two plants by plot with three levels of the factor corresponding to amount of water in the soil (water) and five levels of potassium fertilization (pot). The plots were arranged in five blocks (block). Three response variables are of the interest, namely, grain yield, number of seeds and number of viable peas per plant. This experiment is particularly interesting because we have three response variables of mixed types, i.e., grain yield is a continuous outcome while number of seeds and number of viable peas per plant are examples of count and binomial response variables, respectively. The data set is available in the mcglm package. We started this data analysis by fitting three independent models.

Now, we can easily fit the multivariate model and compare the results.

```
R> fit.joint <- mcglm(linear_pred = c(form.grain, form.seed, form.peas),
+ matrix_pred = list(ZO_ex4, ZO_ex4, ZO_ex4), link = c("identity",
+ "log", "logit"), variance = c("constant", "tweedie", "binomialP"),
+ Ntrial = list(NULL, NULL, soya$totalpeas), data = soya)
R> rbind(gof(list(fit.grain, fit.seed, fit.peas)), gof(fit.joint))

plogLik Df pAIC pKLIC pBIC
1 -339.54 60 799.08 833.0493 1004.0460
2 -319.73 63 765.46 847.7463 980.6743
```

The function gof allows to compute the measures of goodness-of-fit combining one response variable models, assuming that the correlation between the response variables is zero. In that case, the multivariate model provides a better fit than the one response variable models, at least judging by the plogLik, pAIC and pBIC values. The pKLIC tends to strongly penalize models with extra correlation parameters. Thus, we do not recommend to use this measure to compare covariance structures with different number of parameters. On the other hand, the pKLIC is a good choice for comparing covariance structures with a similar number of parameters, as shown in the example in Section 6.3.

The summary output of the model is similar to the one for the one response variable model already presented. The extra feature shown for the multivariate model is the correlation matrix between response variables.

```
R> summary(fit.joint, verbose = TRUE, print = "Correlation")
```

Correlation matrix:

```
Parameters Estimates Std.error Z value

1 rho12 0.63767011 0.1417184 4.4995591

2 rho13 0.07034904 0.1156794 0.6081377

3 rho23 0.08882875 0.1152445 0.7707851
```

Algorithm: chaser Correction: TRUE Number iterations: 10

Furthermore, in this data analysis where a large number of regression coefficients are estimated including interaction effects, the anova function is a convenient way to check the effect significance.

```
2
        water50
                     4.0222
                              2
                                 0.1338
3
                   107.3124
                              4
          pot30
                                 0.0000
4 water50:pot30
                    51.0550
                              8
                                 0.0000
Call: seeds ~ block + water * pot
      Covariate Chi. Square Df p. value
                    19.5163
                                 0.0006
1
        blockII
                              4
2
        water50
                     6.6050
                              2
                                 0.0368
          pot30
3
                    32.1902
                                 0.0000
                    21.3563
4 water50:pot30
                              8
                                 0.0063
Call: viablepeasP ~ block + water * pot
      Covariate Chi. Square Df p.value
1
        blockII
                     7.4417
                                 0.1143
                              4
2
        water50
                     8.8128
                              2
                                 0.0122
3
                   119.2957
                                 0.0000
          pot30
                              4
4 water50:pot30
                    33.6562
                              8
                                 0.0000
```

6.5. Bivariate repeated measures models for count data

In this section we consider the bivariate longitudinal count data analyzed in Bonat et al. (2017) concerning data of animals hunted in the village of Basile Fang, Bioko Norte Province, Bioko Island, Equatorial Guinea. Monthly numbers of blue duikers (BD) and other small animals (OT) shot or snared were collected for a random sample of 52 commercial hunters from August 2010 to September 2013. Covariates available to compose the linear predictors include: ALT, a factor with five levels indicating the altitude where the animal was caught; SEX, a factor with two levels (Female and Male); METHOD, a factor with two levels (Firearm and Snare) and MONTH. The number of hunting days per month is also available in variable OFFSET and should be used as an offset in the models. Here, we present a simplified analysis considering only the repeated measures structure introduced by the observations taken for the same hunter and month (variable HUNTER.MONTH). For a more detailed description of the data and complete analysis we refer to Grande-Vega, Farfán, Ondo, and Fa (2016) and Bonat et al. (2017).

Following Bonat et al. (2017) the linear predictors for BD and OT are specified by:

```
R> data("Hunting", package = "mcglm")
R> form.OT <- OT ~ METHOD * ALT + SEX + ALT * poly(MONTH, 4)
R> form.BD <- BD ~ METHOD * ALT + SEX + ALT * poly(MONTH, 3)</pre>
```

The matrix linear predictor is specified by a linear combination between an identity and a compound symmetry matrix for the HUNTER.MONTH effect.

```
R> Z0_ex5 <- mc_id(Hunting)
R> Z1_ex5 <- mc_mixed(~ 0 + HUNTER.MONTH, data = Hunting)</pre>
```

Finally, we fit the bivariate model using the poisson_tweedie variance function.

We assess the significance of the regression coefficients using the anova function.

```
R> anova(fit1_ex5)
```

```
Wald test for fixed effects
Call: BD ~ METHOD * ALT + SEX + ALT * poly(MONTH, 3)
```

```
Covariate Chi. Square Df p. value
                         3.8902 1 0.0486
1
         METHODTrampa
                 ALT2
                        162.0670 4 0.0000
2
3
              SEXMale 401.4957 1 0.0000
4
      poly(MONTH, 3)1
                      32.3174 3 0.0000
    METHODTrampa:ALT2
                        63.2427 4 0.0000
6 ALT2:poly(MONTH, 3)1
                        71.2614 12 0.0000
```

```
Call: OT ~ METHOD * ALT + SEX + ALT * poly(MONTH, 4)
```

```
Covariate Chi.Square Df p.value
1 METHODTrampa 1.1885 1 0.2756
2 ALT2 158.9866 4 0.0000
3 SEXMale 67.5059 1 0.0000
4 poly(MONTH, 4)1 7.4804 4 0.1126
5 METHODTrampa:ALT2 32.6643 4 0.0000
6 ALT2:poly(MONTH, 4)1 100.8068 16 0.0000
```

The power, dispersion and correlation parameter estimates are provided by the summary.

```
R> summary(fit1_ex5, print = c("power", "Dispersion", "Correlation"))
```

Power:

```
Estimates Std.error Z value 1 1.460708 0.1653851 8.832164
```

Dispersion:

```
Estimates Std.error Z value
1 0.1116979 0.0527109 2.119067
2 0.4577956 0.1386405 3.302034
```

Correction: TRUE

Number iterations: 113

```
Power:
    Estimates Std.error Z value
1    1.799323    0.2482945    7.246727

Dispersion:
    Estimates Std.error Z value
1    0.2052374    0.11454898    1.791700
2    0.5166482    0.09456719    5.463292

Correlation matrix:
    Parameters Estimates Std.error Z value
1         rho12    -0.06845904    0.02904716    -2.356824

Algorithm: chaser
```

The results show that the Pólya-Aepli (p=1.5) and negative binomial (p=2) distributions can be suggested to the response variables BD and OT, respectively. The dispersion structures show the significance of the repeated measures structure for both response variables. The correlation between response variables is weak, but still significantly different from 0.

6.6. Multivariate Tweedie models for spatial areal data

The last example analyzes the spatial distribution of soil chemistry properties measured on a regular grid with 10×25 points spaced by 5 meters. Three continuous response variables are of interest, namely, calcium (CA), magnesium (MG) and potassium (PT) contents. Covariates include the spatial coordinates (COORD.X and COORD.Y), soil pH at water (PHWATER) and the portions of sand (SAND), silt (SILT) and clay (CLAY). The original data set is available in the **geoR** package (Ribeiro Jr and Diggle 2016). The simplified version used here is available in the **mcglm** package.

We model the covariance structure within response variables by combining the tweedie variance function and the conditional auto-regressive model (see Equation 4). The linear and matrix linear predictors for each response variable are specified as follows:

```
R> data("soil", package = "mcglm")
R> form.ca <- CA ~ COORD.X * COORD.Y + SAND + SILT + CLAY + PHWATER
R> form.mg <- MG ~ COORD.X * COORD.Y + SAND + SILT + CLAY + PHWATER
R> form.k <- K ~ COORD.X * COORD.Y + SAND + SILT + CLAY + PHWATER
R> list_neigh <- tri2nb(coords = soil[, 1:2])
R> Z_ex6 <- mc_car(list_neigh = list_neigh)</pre>
```

The estimation of multivariate models is a complex computational task. The choice of good initial values in general helps to reach convergence. A simple strategy to get good initial values consists of fitting separate models for each response variable and then use their estimates as initial values for the multivariate model. In this data analysis, we follow this strategy as shown by the code below.

The initial values for the mcglm function are supplied through a named list, with elements for the regression, power, tau and correlation parameters.

R> ini <- list()

```
R> ini$regression <- list("CA" = coef(fit.ca, type = "beta")$Estimates,
     "MG" = coef(fit.mg, type = "beta")$Estimates,
     "K" = coef(fit.k, type = "beta")$Estimates)
+
R> ini$power <- list("CA" = coef(fit.ca, type = "power")$Estimates,
     "MG" = coef(fit.mg, type = "power")$Estimates,
     "K" = coef(fit.k, type = "power")$Estimates)
R> ini$tau <- list("CA" = coef(fit.ca, type = "tau")$Estimates,
     "MG" = coef(fit.mg, type = "tau")$Estimates,
     "K" = coef(fit.k, type = "tau")$Estimates)
R > ini rho <- c(0, 0, 0)
In the following the multivariate Tweedie model is fitted.
R> fit_ex6 <- mcglm(linear_pred = c(form.ca, form.mg, form.k),</pre>
     matrix\_pred = list(Z\_ex6, Z\_ex6, Z\_ex6), link = c("log", "log", "log"),
     variance = c("tweedie", "tweedie", "tweedie"),
     covariance = c("inverse", "inverse", "inverse"),
     power_fixed = c(FALSE, FALSE, FALSE), control_initial = ini,
     data = soil, control_algorithm = list(max_iter = 100))
```

The users can summarize the model using the summary function or extract parameter estimates using the coef function as well as use all methods available in the mcglm package for analyzing the model results. In particular, for this application the functions mc_compute_rho and mc_conditional_test are tailored tools to compute the spatial auto-correlation and perform conditional hypotheses tests for the dispersion parameters associated with the spatial structure.

7. Discussion

This article described the R implementation of multivariate covariance generalized linear models in the **mcglm** package. The discussed examples illustrate the capability of the package

to deal with various types of data and dependence structures. The models are fitted by an estimating function approach combining quasi-score and Pearson estimating functions for estimation of the regression and dispersion parameters, respectively. The main technical advantage of this approach is the simplicity of the fitting method, which amounts to finding the root for a set of non-linear equations. In this direction, we presented the *modified chaser* and reciprocal likelihood methods. A careful choice of initial values is required for both methods. The fitting process while relying on a simple Newton scoring algorithm also involves computational demanding tasks such as the Cholesky decomposition and multiplication of large matrices. Thus, in the case of large data sets, consisting of several thousands of observations, and models involving many components in the matrix linear predictor, the computational cost may prevent routine use of the **mcglm** package.

The package was designed to take full advantage of the modular specification of the models using a glm style interface. The output of the functions is provided in a way that is easy to interpret for people familiar with standard lm(), glm() or gam() output. Furthermore, a set of methods and auxiliary functions are available for analyzing the model results. The covariance structure within response variable is modeled by combining a matrix linear predictor and a covariance link function. A set of functions for constructing the components of the matrix linear predictor is made available. Furthermore, the users can easily extend the package with new components.

The estimation of the power parameter is, in general, a difficult task. The estimation of the power parameter is particularly challenging when the distribution of the response variable is symmetric for continuous data using the Tweedie variance function. The power parameter is an index that distinguishes between some well known distributions such as the Gamma and inverse Gaussian. All these distributions can provide a good fit for symmetric data. Thus, we do not have enough information in the data to distinguish between these distributions. Therefore, we suggest opting for the simplest possibility i.e., the Gaussian model. Similarly, for count data using the Poisson-Tweedie dispersion function the estimation of the dispersion and power parameters are difficult for equidispersed count data. In such a case the dispersion parameter in the Poisson-Tweedie dispersion function should be zero, which in turn is a value close to the border of the parameter space. Therefore, we suggest again opting for the simplest possibility i.e., the Poisson model obtained by using the Tweedie variance function with power parameter fixed at 1.

Possible topics for further investigation and extensions include facilities for censored data in survival analysis and other special types of data and improvements regarding the residual analysis. In particular, the investigation of how the McGLMs framework can be used to deal with multivariate spatio-temporal data is an interesting topic. Further possible extensions could cover the incorporation of penalized splines in the mean and covariance structures, and the use of regularization for high dimensional data, which would have important applications in genetics. Also of interest would be the construction of new estimating functions to deal with data that are not missing at random and to make prediction using the best linear unbiased predictor (BLUP). Further points worth investigation would be a thorough comparison of the McGLMs framework with more established statistical modeling frameworks such as GEE (generalized estimating equations) models, Gaussian copula regression models, hierarchical generalized linear models and other.

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Affiliation:

Wagner Hugo Bonat Laboratory of Statistics and Geoinformation Department of Statistics Paraná Federal University Centro Politécnico Curitiba 81531980, CP 19081, Paraná, Brazil.

E-mail: wbonat@ufpr.br

URL: http://www.leg.ufpr.br/

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